Approximate Marginal Likelihoods for Shrinkage Parameter Estimation in Penalized Logistic Regression Analysis of Case-Control Data

by

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Dedication

Hörst du: ich rede zu dir, wenn schwül sie das Sterben vermehren. Schweigsam entwerf ich mir Tod, leise begegn ich den Speeren. Ich steh. Ich bekenne. Ich ruf.

Ein Krieger, Paul Celan

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Chapter 1

Introduction

The case-control design is common for genetic epidemiology studies of the relationship between disease status and genetic variants of interest. Case-control studies are retrospective in the sense that subjects are sampled fle Inspired by Firth, Zhang [28] developed a bias-reduced estimator for case-control data. Zhang's estimator is the maximizer of a penalized *profile* likelihood, where the profile likelihood is obtained by maximizing over the infinite-dimensional parameter semiparametric case-control likelihood, and the penalty is like that in the equation (1.1), but with an estimate, \uparrow (), of the Fisher information in the profile likelihood. Simulation studies suggest that the Zhang's method and Firth logistic regression have similar statistical properties when applied to case-control data [6]. The similarity of Firth and Zhang logistic regression suggests that we can apply other penalized logistic regression methods to case-control data.

Alternatives to Firth logistic regression were considered by Greenland and Mansournia.[7]. They recommend penalization by log-F prior distributions over other possible priors such as normal, t- and Cauchy distributions. The family of log-F priors is indexed by a shrinkage parameter *m*. Larger values of *m* induce greater shrinkage. Graham et al.[6] found that the log-F priors performed well in limited simulations of case-control data, but did not propose a method for choosing *m*.

Greenland and Mansournia suggested an empirical Bayes approach to estimating m. The

Chapter 2

Methodology

2.1 Marginal likelihood for Shrinkage Parameter m

Finding the MLE of $_{k}$ is complicated by the in nite-dimensional nuisance parameterg. Qin and Zhang [17] proved that a pro le likelihood function obtained by pro ling g out has the same form as the logistic regression (2.1), with a di erent intercept term $_{k}$.

L(k;k) =

Note that evaluating the integrals in *L* (,*m*) analytically is challenging. A straight-forward way to solve this problem is to apply numerical approximate integration methods such as Gaussian approximation, Monte Carlo integration and quadrature methods. We considered Laplace Approximation in particular, because it is widely used for approximating marginal likelihoods and its simplicity in computation and minimal computation time are advantages over quadrature and MC integration, respectively.



Figure 2.1: The shape of log-F distribution

2.2 Laplace Approximation

Our goal is to approximate the integrals in the marginal likelihood of equation (2.7). Each integral can be viewed as the marginal distribution of the data in a Bayesian problem with likelihood $L(_{k', -k})$ and prior $p(_{kj}m)$. We first discuss theoretical results from the Bayesian inference literature that justify Laplace approximations of marginal distributions when the sample size is large. We then present an empirical investigation of the utility of Laplace approximation in the kinds of small sample problems that we are interested in.

Laplace's method approximates an integral by approximating the integrand with an easyto-integrate function. In particular, the integrand is approximated by an unnormalized Guassian density function whose mean coincides with the mode of the integrand. Suppose our integrand is an un-normalized posterior density P() with $l() = \log P()$. If l() is a smoothfunction w8th t81th

approximation. To investigate the quality of Laplace Approximation in our context we performed limited simulations to assess whether the shape of the unnormalized posterior $L(_k, _k)p(_kjm)$ is close to a normal density function and to judge the quality of Laplace Approximation to the marginal likelihood. The simulations were conducted as described in Chapter 3, with the exception that here we used a small sample of 10 cases and 40 controls. The results are as follows.

For a single covariate simulated under m = 4 a plot of L(1, 1)p(1jm) for m = 4 and = 3 is shown in Figure 2.2, with the approximating unnormalized Gaussian distribution superposed. We can see that the posterior is unimodal (see Appendix A for a proof of unimodality) with a heavier tail than the approximating Gaussian. Overall the approximation looks reasonable for this simulated covariate.



Figure 2.2: The original posterior density for and corresponding unnormalized Normal density

Next we investigate the quality of Laplace Approximation to the marginal likelihood. For each dataset, the marginal likelihood $L(,m) = {}^{R}L(Xj)p(jm)d$ can be regarded as $E_{p}(L(X)j)$, in which indicates the parameter space of . Such an expectation can be estimated by Monte Carlo by sampling 's from the prior distribution and calculating the mean of the likelihood values from each . The precision of such an estimate depends on the Monte Carlo sample size. In the following results we used a Monte Carlo sample size of 1 million.

We compare the approximated marginal likelihood at m = 4 and = 3 from Laplace Approximation, \hat{L}_{LA} , to the estimation from Monte Carlo, \hat{L}_{MC} , for each of 100 simulated single-covariate datasets simulated under m = 4, and calculate the relative di erence $(\hat{L}_{MC} - \hat{L}_{LA})/\hat{L}_{MC}$. In our study, the absolute relative di erence is less than 0.3 in around 75% of the datasets (see Figure 2.3).



Figure 2.3: (f_{MC} f_{LA}) $/f_{MC}$, dashed lines indicating 0.3

Finally, for a single dataset we compared the MC and LA estimates of the marginal likelihood of = 3 and a grid of m = (0.5, 1, 10). We plot the natural log of LA and MC estimates versus m(see figure 2.4). We see that the argmax of the LA-approximated marginal likelihood is smaller than the *argmax* of the MC-approximated marginal likelihood. Whether such underestimation is typical and leads to biased estimation of m is an area for future work.

2.3 Derivative-free Optimization Strategies

We maximize the approximate marginal likelihood, denoted $\mathcal{E}(\ ,m$) to estimate ($\ ,m$). Calculation of derivatives of $\mathcal{E}(\ ,m$) is challenging and so we opted for derivative-free optimization methods. We consider the Nelder-Mead algorithm, a genetic algorithm, and the particle swarm optimization method. The genetic algorithm and particle swarm are examples of the larger class of evolutionary algorithms. We discuss each method briefly in the following subsections. Our simulations (Chapter 3) suggested that the genetic algorithm and the particle swarm optimization method perform better in general. Throughout we let f(x) denote the objective function to be maximized over x in some subset of \mathbb{R}^p .

2.3.1 Nelder-Mead

The Nelder-Mead extended simplex method is most easily described for the case p = 2. Ster.



Figure 2.4: $b (L_{MC})$ and $b (L_{LA})$ for m = 0.5, 1, -10

expanded or contracted at di erent iterations [13], to change the speed at which we move through . For *p*-dimensional we replace triangles with simplexes. Though simple, the Nelder-Mead method is not guaranteed to converge, and there are multiple examples of its failure, even in two dimensions [26, 15]. The Nelder-Mead algorithm is implemented in the R function *optim()* included in the base-R *stats* package [18].

2.3.2 Genetic Algorithm

Genetic algorithms are stochastic search algorithms that equate values of the objective func-

reaches a specified maximum generations. The approach was pioneered by Holland [10] and later generalized; see Corez [4] for a review. A pseudo-code implementation of a genetic algorithm is shown in Algorithm 1 [19] below. In our study we use the ga() function from the R package GA [21].

Algorithm 1: Genetic Algorithm
Result: final population P
Input: evaluation function f , control parameters set C ;
Initialization: random initial population <i>P</i> ;
while termination condition not satisfied do
evaluate current population and get the best individuals E from P ;
select parents set \mathbf{B} from P ;
if crossover condition satisfied then
(d) crossover() ();
end
if mutation condition satisfied then
(d) mutation((d));
end
$P E^{S} \theta$
end

2.3.3 Particle Swarm Optimization

Particle swarm optimization (PSO) is a stochastic optimization technique proposed by Eberhart and Kennedy [12]. An initial set of vectors $x_{1,...,X} = N$ is viewed as "particles" that can move about \therefore The velocity (direction and speed) of the movements are partly random and partly influenced by values of the objective function seen previously by the particle itself and others in its neighbourhood. Various modifications of PSO, and hybrids of PSO and other modern evolutionary optimization algorithms are reviewed by Cortez [4]. Pseudo-code for the SPSO 2007 algorithm of Clerc [3] is given in Algorithm 2 [4]. In our study we use the

psoptim() function from the R package *pso* [2], which implements both the SPSO 2007 and SPSO 2011 algorithms of [3].

_

Algorithm 2: Particle Swarm Optimization
Result : Best solution <i>B</i>
Input: evaluation function f, control parameters set C;
Initialization: initial swarm P, including random position and velocity for each
particle;
get the best particle B;
while termination condition not satisfied do
for each particle $x = ($ $\mathfrak{s} $ $\mathfrak{b} $ $\mathfrak{b} $ $\mathfrak{b} $ $\mathfrak{b} $ $\mathfrak{b} $
update the velocity v by (spb);
move the particle $s + v$;
check if x is on the boundary, if so, adjust;
if s is better fitted than p then $p = \frac{p}{s}$
end
if s is better fitted than B then B s
end
end
update / for all particles following given topology in C;
end

2.4 Summary of Maximum Marginal Likelihood Estimator of m

The approximate marginal likelihood is $\mathcal{P}(\ ,m) = {}^{\mathsf{Q}}_{k=1} \mathcal{R}[Lj ,m]$, where $\mathcal{E}[Lj ,m]$ is the Laplace approximation to ${}^{\mathsf{R}}_{L}(\ ,\)p(\ jm)d$. Each approximate integral $\mathcal{P}[Lj ,m]$

Chapter 3

Simulation Study

Our simulation study addressed two questions:

- 1. Which of Nelder-Mead, the genetic algorithm (GA) or particle swarm optimization (PSO) is the best optimization method for our problem?
- 2. How does the number of genetic markers a lect the bias and variance of our estimator of *m*?

of samples from the prior increases, which in our study is as K increases. We therefore expect bias and variance of the estimator of m to decrease with K. For each simulation configuration we generated 20 data sets.

3.2 Study 1: Optimization Methods Comparison

The methods of Nelder-Mead, GA and the PSO algorithm SPSO 2011 were run with their default settings, and the same initial values of the parameters. An initial value of m = 4 was selected when the true m was 2 or 8, and an initial m = 6 was chosen when the true m was 4. The GA and PSO methods also allow the user to limit the range of m values to search; the search limits we chose are shown in Table 3.1.

True m	Initial m	Method	Setting
		Nelder-Mead	NA
2	4	GA	m 2 f 0, 10g
		PSO	m 2 f 0, 10g
		Nelder-Mead	NA
4	6	GA	m 2 f 0, 10g
		PSO	m 2 f 0, 10g
		Nelder-Mead	NA
8	4	GA	m 2 f 0, 15g
		PSO	m 2 f 0, 15g

Table 3.1: Study 1, simulation setting

The results are shown in Figure 3.1 and Table 3.2. As an indication of performance, the shaded area in each panel is the range $(0.5m \ 1.5m)$. For m = 2, there is no obvious di erence in performance between Nelder-Mead and PSO, while GA tends to overestimate. For m = 4, all three methods provide reasonable estimates of m, though Nelder-Mead always underestimates the true value. Under the largest value m = 8 the estimates from Nelder-Mead appear to be substantially downwardly biased, while the estimates from PSO are highly variable. Overall, GA outperforms the other two methods in terms of accuracy.

Note that there are datasets for which all three methods give similar estimates that are far below the true value. We speculate that for these datasets the simulated

True m	Method	Mean of M	Variance of <i>m</i>





Figure 3.1: Study 1, estimation of *m* for settings of true m = 2, 4, 8 separately

Chapter 4

Real Data Modelling

4.1 Data Description

The Alzheimer's Disease Neuroimaging Initiative (ADNI) is a longitudinal multicenter

Gene	Chromesome	Basepair Start	Basepair End	Number of SNPs
CR1	1	205737551	205881074	15
ECE1	1	21417188	21546592	37
MTHFR	1	11768839	11789631	10
BIN1	2	127534016	127575911	12

Chapter 5

Discussion

Our method of estimating the shrinkage parameter *m* is based on an approximated marginal likelihood. We started from the penalised profile likelihood of the log-OR parameters with a log-F prior, which can be regarded as a modification of Zhang's approach. By approximating the marginal likelihood obtained by integrating out the 's, we can estimate the

other genes we studied we were not able to obtain trustworthy estimates of m and would recommend a large value of m=10, or a Gaussian prior. The genetic covariates in the ADNI-1 study were 0, 1, 2 counts, which di ered from the data generation in our simulations. An area of future work is to conduct simulations with sparse count covariates.

A shortcoming of this project is that our method is not appropriate for low-dimensional datasets. Information about the shrinkage parameter *m* comes from multiple realizations from the prior distribution and we therefore need multiple covariates. By contrast, very high-dimensional datasets pose computation problems and may lead to poor performance of the optimization methods. For example, Helwig and Wanka [9] showed that the initialization and bound handling mechanism of particle swarm optimization can cause particles to become trapped at local maxima in high-dimensional search spaces.

The major limitation of this work is that it does not provide confidence intervals for our estimates of the shrinkage parameter m. One possible approach is to obtain confidence intervals by inverting a profile likelihood ratio test. The profile likelihood is obtained as follows. For fixed m we consider the marginal log-likelihood to be a function of the structure optimization method to maximize this function over the structure obtain an approximate profile likelihood value at m. Repeating this procedure for a grid of m values gives an approximate profile log-likelihood for m. A profile likelihood ratio test of a specific value m_0 would retain the null hypothesis when 2 times the log-likelihood ratio of m_0 versus m is less than about 4. This reasoning leads to the so-called "drop-down-two" confidence interval comprised of all m_0 such that the estimated profile log-likelihood at m_0 is within about 2 of the estimated profile log-likelihood at m. Investigation of the properties of such an approach can be included in the future work.

Ultimately, the purpose of estimating m is to use it as the smoothing parameter in single-SNP logistic regression analyses. It is therefore of interest to explore the statistical properties of the log-OR estimator from the two-step process of first estimating m and then estimating log-ORs under a log-F(m,m) penalty. In addition to considering the approximate maximum likelihood estimator m, we might also use the m value at, say, the upper or lower limits of the confidence interval for m. These explorations are also future work.

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[12]

Appendix A

Implementation of Laplace Approximation

Recall the marginal likelihood for (m, m) and denote the product L(k, k)p(kjm) by L_p , which can be regarded as an unnormalized posterior density. Note that L_p is dimensional erentiable, and denote the maxima of L_p with k, m given, as $k^{max} \cdot L_p d_k$ can be approximated with

$$\mathcal{L}_{pj} \underset{k}{\overset{\text{max}}{\underset{k}{\text{max}}}} \frac{s}{\frac{2}{C_{p}}} \mathcal{L}_{p} = -\frac{2}{k} g (\mathcal{L}_{p}) j \underset{k}{\overset{\text{max}}{\underset{k}{\text{max}}}}$$
(A.1)

In Practice, the value of L_p can be too small to compute in R, instead we computed g (L_p) to access the value of $\frac{max}{k}$ by simply taking the derivatives. Plug-in (2.4) and (2.5) we have

$$\frac{g}{k} = \sum_{i=1}^{k} \left(Y_i X_i^k - \frac{g(k+X_i^k)X_i^k}{1+g(k+X_i^k)} - \frac{m}{2} + m\frac{g(k)}{1+g(k-k)} \right)$$
(A.3)

To show that L_p is well-peaked enough for Laplace approximation, we prove the following result to ensure its unimodality:

Result The root of $(L_p)/k = 0$, denoted by k^{max} , is the global maxima of L_p . **Proof** Rewrite (A.3) with notations of $e = p (k), e_k = p (k)$, we have

$$\frac{X^{n}}{1+e} \left(Y_{i}X_{i}^{k} - \frac{e}{1+e} \frac{e_{k}^{X_{i}^{k}}X_{i}^{k}}{1+e}\right) - \frac{m}{2} + m\frac{1 e_{k}}{1+1 e_{k}} = \frac{X^{n}}{1+1} \left(Y_{i}X_{i}^{k} - X_{i}^{k}\right) + \frac{X_{i}^{k}}{1+1 e_{k}} + \frac{X_{i}^{k}}{1+1 e_{k}} = \frac{X^{n}}{1+1} \left(Y_{i}X_{i}^{k} - X_{i}^{k}\right) + \frac{X_{i}^{k}}{1+1 e_{k}} + \frac{X_{i}^{k}}{1+1 e_{k}} = \frac{X^{n}}{1+1} \left(Y_{i}X_{i}^{k} - X_{i}^{k}\right) + \frac{X_{i}^{k}}{1+1 e_{k}} + \frac{X_{i}^{k}}{1+1 e_{k}} = \frac{X^{n}}{1+1} \left(Y_{i}X_{i}^{k} - X_{i}^{k}\right) + \frac{X_{i}^{k}}{1+1 e_{k}} + \frac{X_{i}^{k}}{1+1 e_{k}}$$

Consider when $_{k}$! 1 ; e_{k} ! 0, $\frac{X_{i}^{k}}{1+e} e_{k}^{\times k}$! X_{i}^{k} when $X_{i}^{k} > 0$; ! 0 when $X_{i}^{k} < 0$. Then

$$\frac{X^{n}}{i=1} (Y_{i}X_{i}^{k} X_{i}^{k} + \frac{X_{i}^{k}}{1 + e e_{k}^{X_{i}^{k}}}) \frac{m}{2} + \frac{m}{1 + e_{k}}$$

$$\frac{X^{n}}{1 + e_{k}} (Y_{i}X_{i}^{k} X_{i}^{k}) + \frac{X^{n}}{1 + e e_{k}^{X_{i}^{k}}} X_{i}^{k} | (X_{i}^{k} > 0) + \frac{m}{2}$$

$$= \frac{X^{n}}{i=1} (Y_{i}X_{i}^{k}) \frac{X^{n}}{i=1} X_{i}^{k} | (X_{i}^{k} < 0) + \frac{m}{2}$$

$$= \frac{X^{n}}{i=1} (X_{i}^{k} | (Y_{i} = 1) | (X_{i}^{k} > 0) X_{i}^{k} (Y_{i} = 0) | (X_{i}^{k} < 0)) + \frac{m}{2} > 0$$
(A.5)

Similarly, when $_{k}$! 1 ; e_{k} ! 1 , $\frac{X_{i}^{k}}{1+e e_{k}^{X_{i}^{k}}}$! 0 when $X_{i}^{k} > 0$; ! X_{i}^{k} when $X_{i}^{k} < 0$. We

have

$$\frac{X^{n}}{i=1} (Y_{i}X_{i}^{k} X_{i}^{k} + \frac{X_{i}^{k}}{1 + e e_{k}^{X_{i}^{k}}}) \frac{m}{2} + \frac{m}{1 + e_{k}}$$

$$\frac{X^{n}}{i=1} (X_{i}^{k}I(Y_{i} = 1)I(X_{i}^{k} < 0) X_{i}^{k}(Y_{i} = 0)I(X_{i}^{k} > 0)) \frac{m}{2} < 0$$
(A.6)

Since (A.3) is continuous on R, a root of $@logL_p) = @_k = 0$ must exist according to intermediate value theorem. Next we prove this root, denoted by k_k^{max} is the only root. The Hessian

 $\frac{\mathscr{B}}{\mathscr{B}_{k}^{2}}\log(L_{p}) = \sum_{i=1}^{X^{n}} (exp(_{k} + X_{i}^{k}_{k})(X = 0 \quad n \neq u \neq 0 \text{ is } t \neq 0 \text{ is } t \neq 0 \text{ in } t \neq 0 \text{ in$









(c) MTHFR

(d) BIN1



Figure B.1: LDheatmaps for genes included in real data analysis section, using R^2 measure of LD(part 1)



(a) IL33

(b) SORCS11



(c) GAB2

(d) PICALM



Figure B.2: LDheatmaps for genes included in real data analysis section, using R

Appendix C

Code

```
library (pso)
library (GA)
n<-1000
 1
 2
 3
      mo<-2 #the prior density of beta is log-F
 4
      p<-19
 5
      simUnmatched =function (n,p,scale= FALSK
 6
         # n is total sample size, beta1 is value of parameter of interest,
# p is number of nuisance covariates.wqs
 7
 8
         ConCaseRatio = 4 # assuming 4:1 con:case ratio
ncase = n/(ConCaseRatio+1); ncon=ncase*ConCaseRatio
beta = log (rf(p+1,mo/2,mo/2)) # p nuisance params o
 9
10
                                                         # p nuisance params of value 1
11
         ncov = p+1
12
         # Simulate cases and controls
conX = caseX =NULL
for (i in 1:ncov) {
    conX = cbind (conX,rnorm(ncon,mean=0,sd=1))
13
14
15
16
             caseX = cbind (caseX,rnorm(ncase,mean= beta[i],sd=1))
17
18
         X = rbind (caseX, conX)
19
         colnames(X) = paste0 ("x",1:ncov);
                                                                rowname($X) = NULL
20
21
         case = C
```

```
alpha_star0<-alpha_star0m0[di]
50
                 X<-XM[,di]
51
                 temp1<-sum(X^2* exp(alpha_star0+beta_max[di]*X)/(1+
                                                                                    exp(alpha_star0+beta_max[di]*X)))
52
                 - sum(X^2*( exp(alpha_star0+beta_max[di]*X)/(1+
                                                                             exp(alpha_star0+beta_max[di]*X)))^2)
53
                 temp2<-exp(-beta_max[di])/(1+ exp(-beta_max[di])))
-( exp(-beta_max[di])/(1+ exp(-beta_max[di])))^2
 54
55
                 c=temp1+m0*temp2
56
                 LP_di<- sum(y*(alpha_star0+beta_max[di]*
57
                                                                     as.numeric (X))
                 - log (1+exp(alpha_star0+beta_max[di]*
                                                                as.numeric (X)))
58
                 - log ( beta (m0/2,m0/2))-m0/2*beta_max[di]-m0* log (1+exp(-beta_max[di]))-0.5*
II<-II+LP_di
                                                                                                                   log (c)
59
60
 61
              }
62
63
            pso.result<-psoptim(par=
                                           c(alpha_star.V,m),fn=multi.dimen.logLP_betamax,
64
           lower=c(rep(-20,p+1), 0), upper = c(rep(10,p+1),15),control=
maxit=3000,maxit.stagnate=50,s=50,type="SPSO2011"))
                                                                                            list (trace=100.fnscale=-1.
65
66
            if (abs(pso.result$value-ftracer)>=0.001*
                                                                 abs(ftracer)){
67
              alpha_star.V=pso.result$par[1:(p+1)]
m=pso.result$par[p+2]
68
69
               tracer - rbind (tracer,
                                          c(as.integer (i),alpha_star.V,m,pso.result$value))
 70
              ftracer<-pso.result$value
 71
              print (tracer[i+1,])
72
            } else {
 73
              break
 74
           }
75
 76
         tracer
 77
78
      NMLA function (alpha_star.V,m,n.rounds){
 79
         tracer<- matrix (0,nrow=1,ncol=p+4)
80
         ftracer<-0
81
 82
         i=1
              (i in 1:n_rounds){
83
         for
            beta_max<-numeric(p+1)
84
            for (di in 1:(p+1)){
 85
               X<`-XM[,di]
86
               alpha_star<-alpha_star.V[di]
87
               dlogPenalisedL<- function (beta){
88
                 sum(X*y-(X* exp(alpha_star+ beta * as.numeric (X))
89
                 /(1+ exp(alpha_star+ beta * as.numeric (X)))))
90
                 -m/2+m*exp(- beta)/(1+ exp(- beta))
91
 92
              beta_max[di]<-uniroot(dlogPenalisedL,
                                                                 c(-20,20))$root
93
 94
            multi.dimen.logLP_betamax<- function (alpha_star0m0){
 95
              m0=alpha_star0m0[p+2]
96
               I<-0
97
              for (di in 1:(p+1)){
 98
                 alpha_star0<-alpha_star0m0[di]
99
                 X<-XM[,di]
100
                 temp1<-sum(X^2* exp(alpha_star0+beta_max[di]*X)/(1+
                                                                                    exp(alpha_star0+beta_max[di]*X)))
101
                 - sum(X^2*( exp(alpha_star0+beta_max[di]*X)/(1+ etemp2<-exp(-beta_max[di])/(1+ exp(-beta_max[di]))
                                                                             exp(alpha_star0+beta_max[di]*X)))^2)
102
                 temp2<-exp(-beta_max[di])/(1+
103
                 -( exp(-beta_max[di])/(1+
                                                 exp(-beta_max[di])))^2
104
                 c=temp1+m0*temp2
105
                 LP_di<- sum(y*(alpha_star0+beta_max[di]* as.numeric (X))- log (1+exp(alpha_star0+beta_max[di]* as.numeric (X))))
+beta_max[di]* as.numeric (X))))
- log ( beta (m0/2,m0/2))-m0/2*beta_max[di]-m0* log (1+exp(-beta_max[di]))-0.5*
                                                                     as.numeric (X))- log (1+exp(alpha_star0
106
107
                                                                                                                   log (c)
108
                 II<-II+LP_di
109
110
              Ì
111
112
                                         c(alpha_star.V,m),fn=multi.dimen.logLP_betamax,
            opt.result<-optim(par=
113
            method="Nelder-Mead",control = list (fnscale=-1))
114
              (abs(opt.result$value-ftracer)>=0.001*
                                                                 abs(ftracer)){
            if
115
              alpha_star.V=opt.result$par[1:(p+1)]
m=opt.result$par[p+2]
116
117
                                         c(as.integer (i),alpha_star.V,m,opt.result$value))
              tracer -- rbind (tracer,
118
119
              ftracer<-opt.result$value
              print (tracer[i+1,])
120
            } else {
121
              break
122
```