Multi-sensor Inertial Navigation

Status: Available

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Project Description

The goal is to develop an Inertial Measurement Unit based on using multiple sensors in parallel
to improve accuracy and stability of the system. A challenge with existing IMUs based on
microsensors is t.6 TJ   -15.13 -1.152 Td   [(ar)-6 (e)11.3 (t)-6.6 (hen c)-2 (o)10.5 (m)-6 (bi)2.6 (ned us)-2 (i)2.6
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