Multi-sensor Inertial Navigation

Status: Available

Group Members:

Sponsor(s): Intelligent Sensing Laboratory (ISL)

Supervisor(s): Behraad Bahreyni, PhD, PEng, Associate Professor, Mechatronic

Systems Engineering

Project Description

The goal is to develop an Inertial Measurement Unit based on using multiple sensors in parallel to improve accuracy and stability of the system. Aeshalletmenters to improve accuracy and stability of the system.